

### Summary Method C3 (Jun '12)

1.

Apply the mid-ordinate rule from the formula book, defining  $x_0$  to  $x_3$  and then using  $x_{0.5}$ ,  $x_{1.5}$  and  $x_{2.5}$  to find the corresponding  $y$  ordinates.

2.

a)

Begin to solve simultaneously by eliminating  $y$ , and rearrange to produce an equation of the form  $f(x) = 0$ . Then demonstrate that  $f(0.5)$  and  $f(1.5)$  lie either side of zero (one positive, one negative).

b)

Divide by 4, then use the fact that  $e^x$  is the inverse function of  $\ln x$  to complete the rearrangement.

c)

Substitute in the value given for  $x_1$  to calculate  $x_2$ , and use your value for  $x_2$  (in as accurate a form as possible) to find  $x_3$ . Then give answers to required level of accuracy.

d)

Draw a line from  $x_1$  up to the curve, then horizontally from that point to the line  $y = x$ . A dotted line vertically downwards from here gives the value of  $x_2$  on the  $x$ -axis. From this point, draw a line vertically to the curve once again, and again horizontally to meet the line  $y = x$ . Repeat until all  $x$  values are represented.

3.

a)

Use the product rule (first term  $\times$  differential of second + second term  $\times$  differential of first).

b)

i.

Substitute  $x = e$  into your expression for  $\frac{dy}{dx}$  to find the gradient of the tangent at that point. Substitute  $x = e$  into the original function to find the co-ordinates of the point, and use  $y - y_1 = m(x - x_1)$  to find the equation of the tangent at that point.

ii.

Substitute  $y = 0$  into your equation for the tangent line, and solve. Note: an exact value is required, so leave in terms of  $e^k$  where appropriate.

4.

a)

Set  $u = x$  in order to simplify the result. Use the Integration by Parts formula from the formula book.

b)

Recall the required integral for a volume of revolution about the  $x$ -axis:  $V = \int \pi y^2 dx$ . After simplifying, this should closely resemble the integral from part a), and be readily calculable. Ensure your answer is left in the form specified.

**5.**

a)

Recall that  $\sqrt{x}$  cannot be negative (otherwise it would be written as  $\pm\sqrt{x}$ ).

b)

i.

Recall that  $fg(x) = f(g(x))$ . Substitute the function  $g(x)$  into the function  $f(x)$  in place of  $x$ .

ii.

Set your answer to b)i. equal to 5, rearrange and solve for  $x$ .

c)

i.

Set  $f(x) = y$ , then rearrange to find  $x$  in terms of  $y$ , then interchange  $x$  and  $y$ . Replace  $y$  with  $f^{-1}(x)$ .

ii.

Set your answer to c)i. equal to 7, rearrange and solve for  $x$ .

**6.**

Find  $\frac{du}{dx}$  and use this to replace  $dx$ , along with part of the numerator. Replace any instances of  $x^4 + 2$  with  $u$ , and replace any other instances of  $x$  with an equivalent expression in  $u$ . Make sure you give the answer in the required form.

**7.**

a)

Recall that  $|f(x)| = f(x)$  when  $f(x) \geq 0$  and  $|f(x)| = -f(x)$  when  $f(x) < 0$ .

b)

Consider negative values of  $x$ , and how they will be interpreted by the function  $f(|x|)$ .

c)

Recall that  $af(x)$  represents a stretch in the  $y$ -direction with scale factor  $a$ , and  $f(x + b)$  represents a translation of  $\begin{bmatrix} -b \\ 0 \end{bmatrix}$ .

d)

Use the sequence of transformations you have described to find the new maximum point. Note that a stretch in the  $y$ -direction will multiply the distance of each point from the  $x$ -axis by the scale factor.

**8.**

a)

Adding the fractions using the standard common-denominator method will yield expressions in both the numerator and denominator which simplify using  $\sin^2 \theta + \cos^2 \theta = 1$ .

b)

Use the proven simplification from part b) to rewrite this equation in terms of  $\operatorname{cosec}^2 \theta$ , then rearrange and solve for  $\sin x$ , and finally for  $x$ . Make sure answers are given from the required range and to the required level of accuracy,

9.

a)

The quotient rule is given in your formula book.

b)

A variation on  $\sin^2 \theta + \cos^2 \theta = 1$  links  $\tan \theta$  and  $\sec \theta$ .

c)

Rearrange to give  $x$  in terms of  $y$ , find  $\frac{dx}{dy}$  using the result from part a), then use the result that  $\frac{1}{\frac{dx}{dy}} = \frac{dy}{dx}$ ,

along with the result from part b), to prove the required result.

d)

i.

Differentiate to find  $\frac{dy}{dx}$  using the result from part c). Set the resulting expression equal to 0, rearrange and solve to find  $x$  ordinates for stationary points.

ii.

Use quotient rule to differentiate your expression for  $\frac{dy}{dx}$  from part d)i.

iii.

Substitute your  $x$  values for stationary points into your expression for  $\frac{d^2y}{dx^2}$  from part d)ii. to find any which are minimum ( $\frac{d^2y}{dx^2} > 0$ ). Confirm that this value of  $x$  corresponds to a value of  $y = 0$  to show that the point lies on the  $x$ -axis.